# Optimal Transport and Geometric Inequalities

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### Aim

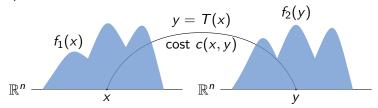
Present some applications of Optimal Transport to geometric inequalities for smooth/non-smooth manifolds.

### Plan

- General overview on Optimal Transport
- Theory of Curvature-Dimension condition
- Functional Inequalities: Levy-Gromov isoperimetric inequality

# **Optimal Transport: Formulation**

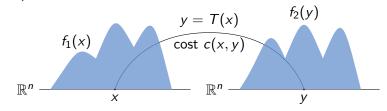
*How to minimise total transport cost?* (Monge 1781, Kantorovich 1942)



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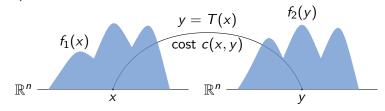
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If  $\int f_1 = \int f_2$ , T is a *transport map* from  $f_1$  to  $f_2$  iff for any  $A \subset \mathbb{R}^n$  $\int_A f_2(x) \, dx = \int_{T^{-1}(A)} f_1(x) \, dx, \quad i.e. \ T_{\sharp}(f_1 \, dx) = f_2 \, dx,$ 

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Given a cost fuction c(x, y), the *total transport cost* of T is

$$C(T) = \int_{\mathbb{R}^n} c(x, T(x)) f_1(x) \, dx.$$

# Optimal Transport: Monge problem

Monge Optimal transport problem minimize

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,  $T$  transport map from  $f_1$  to  $f_2$ .

Main issues with the minimization problem

- ➤ T is (smooth) transport map iff f<sub>2</sub>(T(x))| det DT(x)| = f<sub>1</sub>(x). Highly non-linear constrain.
- The set of transport maps is not closed in any reasonable topology.
- ▶ Replace f<sub>1</sub>, f<sub>2</sub> with any µ<sub>1</sub>, µ<sub>2</sub> ∈ P(ℝ<sup>n</sup>) to obtain the general Monge problem: the set of transport maps can be empty.

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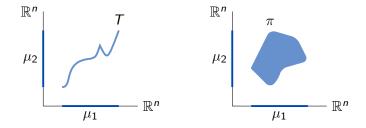
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- $\rightsquigarrow$  Kantorovich relaxation rewrite the total transportation cost

$$\int_{\mathbb{R}^n} c(x, T(x))\mu_1(dx) = \int_{\mathbb{R}^n \times \mathbb{R}^n} c(x, y)((id, T)_{\sharp}\mu_1)(dxdy)$$

## Optimal Transport: Monge-Kantorovich problem

A transport map T seen as a measure on its graph  $(id, T)_{\sharp}\mu_1$ becomes a *transport plan* 

 $\Pi(\mu_1,\mu_2) = \{\pi \in \mathcal{P}(\mathbb{R}^n \times \mathbb{R}^n) \colon (\mathcal{P}_i)_{\sharp}\pi = \mu_i, \ i = 1,2\}.$ 



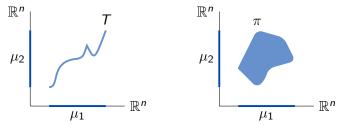
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Set of transport plans is weakly closed and convex. Monge-Kantorovich problem minimize the linear functional

$$\Pi(\mu_1,\mu_2) \ni \pi \mapsto \int_{\mathbb{R}^n \times \mathbb{R}^n} c(x,y) \pi(dxdy).$$

If  $c : \mathbb{R}^n \times \mathbb{R}^n \to [0, \infty)$  is l.s.c., existence of a solution.

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•  $X = M^n$  Riem. mfld  $c = d_g$  (Feldman, McCann).

Given  $\mu_1, \mu_2$  there exists  $u: X \to \mathbb{R}$  1-Lipschitz function so that

$$\pi$$
 optimal  $\iff \pi(\{(x,y) \colon u(x) - u(y) = d_g(x,y)\}) = 1.$ 

Optimal path for  $c = d_g$  are along steepest descent of u.

Flexible problem, has found applications in many fields (different choices of c).

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- ► Analysis and PDEs: Gradient flows, JKO scheme. Monge-Ampere equation (c(x, y) = |x - y|<sup>2</sup>).
- Physics: Random matching problem (sqrd Eucl. dist.), Density Functional Theory (Coulomb cost), Einstein equation of general relativity (Lorentzian cost function).
- Geometry of metric spaces: new class of metric spaces by Lott-Sturm-Villani verifying *Ric* ≥ *K* and *dim* ≤ *N* in a synthetic sense, called CD(*K*, *N*).
- Data science and Economy: Entropic regularisation (Sinkhorn, Shrodinger problem), mixed problems (Hellinger-Kantorovich).

## Geometry of metric spaces: basics

Let  $(M^n, g)$  be an *n*-dimensional Riemannian manifold. Denote *Sec* the sectional curvature and *Ric* the Ricci curvature.

- For K ∈ ℝ we write Sec ≥ K (resp.≤ K) if for every p ∈ M and every 2-dim plane Π ⊂ T<sub>p</sub>M it holds Sec<sub>p</sub>(Π) ≥ K (resp. ≤ K).
- ▶  $Ric_p: T_pM \times T_pM \to \mathbb{R}$  is a quadratic form. We write  $Ric \ge K$  (resp.  $\le K$ ) if the quadratic form  $Ric_p Kg_p$  is non-negative (resp. non-positive) definite at every  $p \in M$ .

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Examples

- *n*-dimensional euclidean space:  $Sec \equiv 0, Ric \equiv 0$ .
- ▶ *n*-dimensional round sphere of radius 1:  $Sec \equiv 1$ ,  $Ric \equiv n 1$ .

▶ *n*-dimensional hyperbolic space:  $Sec \equiv -1$ ,  $Ric \equiv -(n-1)$ .

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▶ *n*-dimensional hyperbolic space:  $Sec \equiv -1, Ric \equiv -(n-1)$ . Natural question (M, g) smooth Riem. manifold. Assume some upper/lower bounds on *Sec* or on *Ric*; what can we say on (M, g)?

### Basics on comparison geometry

- Upper/Lower bounds on the Sec are strong assumptions with strong implications (definition of Alexandrov spaces: non smooth spaces with upper/lower bounds on Sec).
- ► Upper bounds on the Ricci curvature are very (too) weak assumption for geometric conclusions. Lokhamp Theorem: any closed mfld of dim ≥ 3 carries a metric with negative Ric.

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Lower bounds on the Ric natural framework for comparison geom.

▶ Bishop-Gromov volume comparison: If  $Ric \ge 0$  then for all  $x \in M$   $R \rightarrow vol_g(B_R(x))/\omega_N R^N$  is monotone non-increasing

- Laplacian comparison,
- Cheeger-Gromoll splitting,
- Levy-Gromov isoperimetric inequality

Gromov in the '80ies:

notion of convergence for Riemannian manifolds: Gromov-Hausdorff convergence (for non-compact manifolds, more convenient a pointed version, called pointed Gromov-Hausdorff convergence ~ GH-convergence of metric balls of every fixed radius).

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Big Question what about the compactification of the space of Riem. mfld with Ricci curvature bounded below (by, say, -1)? Hope useful also to establish properties for smooth manifolds.

Cheeger-Colding 1997-2000: three fundamental works on the structure of Ricci limit spaces.

Non-intrinsic point of view consider the non-smooth space arising as limits of smooth objects. Dichotomy collapsing (loss of dim in the limit)-non collapsing. Very powerful for local struct. properties.

Analogy Define  $W^{1,2}$  as completion of  $C^{\infty}$  endwed with  $W^{1,2}$ -dist.

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 $W^{1,2}$  can be defined also in completely intrinsic way without passing via approximations (very convenient for doing calculus of variations).

Role of OT define in an intrisic-axiomatic way a non-smooth space with Ricci curvature bounded below by K and dimension bounded above by N (containing ricci limits no matter if collapsed or not).

 $\implies$  Weak version of a Riemannian manifold with  $Ric \geq K$ .

# Optimal Transport: Cornerstone

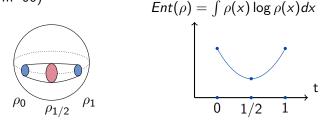
Interplay of Optimal Transport, entropy and curvature

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▶ **Ricci curvature** in terms of geodesic convexity of entropy along  $L^2$  Optimal Transport,  $c(x, y) = d_g^2(x, y)$  (Lott-Villani, Sturm '06)



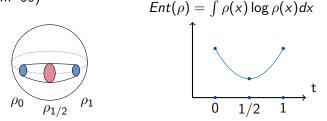
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► LSV theory: new approach to non-smooth metric spaces Examples: manifolds with *Ric* ≥ *K*, Alexandrov spaces, normed and Finsler spaces, limits of those spaces