

more on

Conjugate Gradients
Diagonalization

Conjugate Gradients Diagonalization

- For each band, given a trial eigenpair: $\{|\phi_i^{(n)}\rangle, \varepsilon_i\}$

- Minimize the single particle energy

$$E(|\phi_i\rangle) = \langle \phi_i | H_{KS} | \phi_i \rangle$$

by (pre-conditioned) CG method

subject to the constraints

$$\langle \phi_i | S | \phi_j \rangle = \delta_{ij}, \quad \forall j \leq i$$

- Repeat for next band until completed

Steepest Descent Minimization

$$f(x) = \frac{1}{2}xAx - bx$$

$$g(x) = -\nabla f(x) = b - Ax$$

$$x = x_0 \quad g_0 = b - Ax_0$$

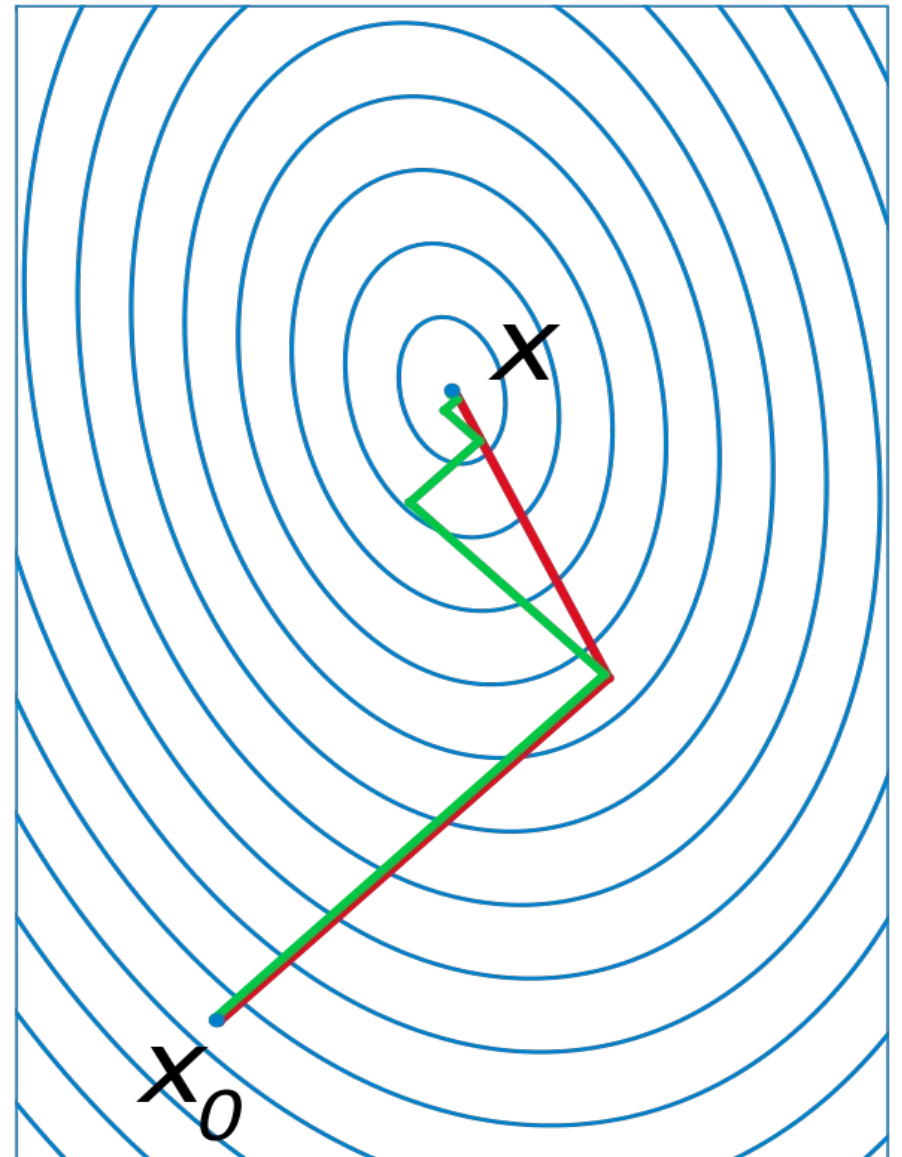
$$x_{k+1} = x_k + \lambda g_k$$

$$g_{k+1} = g_k - \lambda Ag_k$$

$$\lambda = \frac{g_k g_k}{g_k A g_k}$$

subsequent minimizations
are orthogonal !

keep updating the same
directions !



Conjugate Gradients Minimization

$$f(x) = \frac{1}{2}xAx - bx$$

$$g(x) = -\nabla f(x) = b - Ax$$

$$x = x_0 + \sum_k \alpha_k h_k$$

$$g_0 = b - Ax_0$$

$$f(x) = f(x_0) + \frac{1}{2} \sum_{kl} \alpha_k h_k Ah_l \alpha_l - \sum_k g_0 h_k \alpha_k$$

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If conjugate directions are considered: $h_k Ah_l = 0$ for $k \neq l$

$$f(x) = f(x_0) + \frac{1}{2} \sum_k \alpha_k^2 h_k Ah_k - \sum_k g_0 h_k \alpha_k$$

each term add to the solution w/o spoiling previous steps.
after N steps the minimization terminates at the minimum.

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$$x_0, g_0, h_0 = g_0$$

$$x_{k+1} = x_k + \alpha_k h_k$$

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$$\text{because } h_l Ah_k = 0, \quad \forall l < k$$

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$$h_{k+1} Ah_k = 0 \implies \beta_k = -\frac{h_k Ag_{k+1}}{h_k Ah_k} = \frac{g_{k+1} g_{k+1}}{g_k g_k}$$

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Conjugate Gradients Minimization (general)

$$f(x) \approx \frac{1}{2}xAx - bx \qquad g(x) = -\nabla f(x)$$

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$$x_{k+1} = x_k + \alpha_k h_k \qquad \alpha_k = \frac{g_k g_k}{h_k Ah_k} \text{ replaced with line minim}$$

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$$h_{k+1} = g_{k+1} + \beta_k h_k$$

Fletcher-
Reeves

Polak-
Ribiere

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If conjugate directions are considered: $h_k Ah_l = 0$ for $k \neq l$

The method is guaranteed to converge after N steps.

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The method is guaranteed to converge after N steps.

Not very appealing if N is very large.

Preconditioned Conjugate Gradients Minimization

$$f(x) = \frac{1}{2}xAx - bx \qquad g(x) = -\nabla f(x) = b - Ax$$

Define $x = Py$ such that $PAP \approx \text{const}$

Apply the algorithm to the transformed problem

Preconditioned Conjugate Gradients Minimization

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$$y_0, \tilde{g}_0 = P(b - APy_0), \tilde{h}_0 = \tilde{g}_0$$

$$\alpha_k = \frac{\tilde{g}_k \tilde{g}_k}{\tilde{h}_k PAP \tilde{h}_k}$$

$$y_{k+1} = y_k + \alpha_k \tilde{h}_k$$

$$\tilde{g}_{k+1} = \tilde{g}_k - \alpha_k PAP \tilde{h}_k$$

$$\beta_k = \frac{\tilde{g}_{k+1} \tilde{g}_{k+1}}{\tilde{g}_k \tilde{g}_k}$$

$$\tilde{h}_{k+1} = \tilde{g}_{k+1} + \beta_k \tilde{h}_k$$

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$$x_k = Py_k, \quad h_k = P\tilde{h}_k, \quad g_k = P\tilde{g}_k$$

Apply the algorithm to the transformed problem

$$x_0, \quad g_0 = P^2(b - Ax_0), \quad h_0 = g_0$$

$$\alpha_k = \frac{g_k P^{-2} g_k}{h_k A h_k}$$

$$x_{k+1} = x_k + \alpha_k h_k$$

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