

Non-linear reduction for data-driven non-intrusive reduced-order models with parallel autoencoders



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Introduction

The completely data-driven non-intrusive ROM using linear reduction methods such as the POD fails for problems characterised by a slow decay of the Kolmogorov N-width. In this ongoing research, we are exploring the usage of a **non-linear reduction** approach such as the **autoencoder** neural network instead of the linear POD, to tackle various types of problems within the **HPC** framework, taking the advantage of **data parallelism** techniques.

1 - The traditional data-driven non-intrusive ROM

Using Proper Orthogonal Decomposition with Interpolation (PODI):

Starting from a parametric geometrical model; if we have a database of parameter val- Q: How to get value of the modal coefficients α for each new parameter? ues $\boldsymbol{\Xi} = [\boldsymbol{\mu}_1 \dots \boldsymbol{\mu}_N]$ and a database of snapshots $\boldsymbol{\Theta} = [u(\boldsymbol{\mu}_1) \dots u(\boldsymbol{\mu}_N)]$ as in [1], we can apply the Singular Value Decomposition (SVD) to the snapshots matrix Θ :

 $\Theta = \Psi \Sigma \Phi^T$

In the offline phase: We compute the full-order solution using the high-fidelity solver for some parameter points $\mu_k \in \Xi$. Since the high fidelity solution $u(\mu_k)$ and the reduced solution $u^{N}(\mu_{k})$ are assumed to be equal by construction, we have the following:

$$\forall \boldsymbol{\mu}_{k} \in \boldsymbol{\Xi} : u(\boldsymbol{\mu}_{k}) = u^{N}(\boldsymbol{\mu}_{k}) = \sum_{i=0}^{N} \alpha_{i}(\boldsymbol{\mu}_{k}) \psi_{i}$$

where Ψ and Φ are the left and right singular vectors matrices of Θ , and Σ is the diagonal matrix containing the singular values in decreasing order. The columns of Ψ are called the **POD modes** ψ and the modal coefficients α can be obtained through $\alpha = \Psi^T \Theta$ as mentioned in [2].

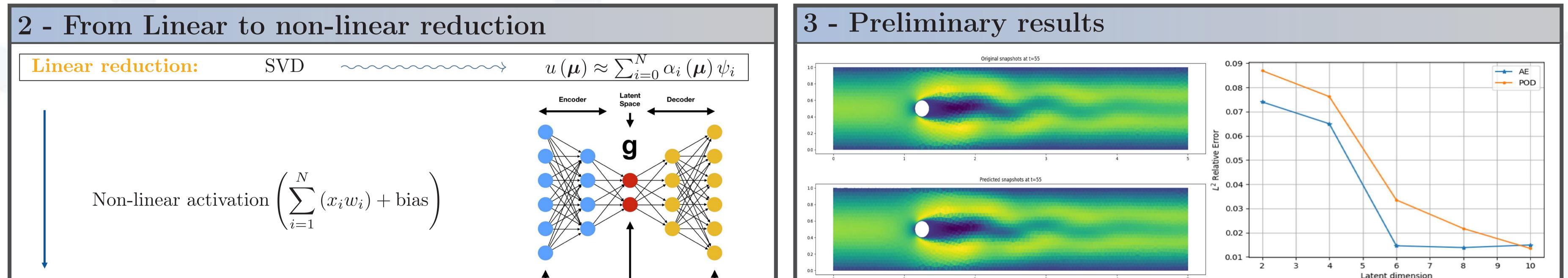
Then the reduced solution of the problem can be viewed as a linear combination of the POD modes ψ multiplied by the modal coefficients α as follows:

 $u^N = \sum_{i=0}^N \alpha_i \psi_i$

Now for the set of parameters μ_k , we can compute the corresponding coefficients $\alpha(\mu_k)$.

In the online phase: Since we obtained pairs of $(\mu_k, \alpha(\mu_k))$, for each new parameter μ_{new} , we interpolate the previously computed coefficients $\alpha(\mu_k)$ to find the new coefficients $\alpha(\mu_{new})$. The new reduced solution can be obtained by:

$$u_{new}^{N} = \sum_{i=0}^{N} \alpha_i \left(\boldsymbol{\mu}_{new} \right) \psi_i$$



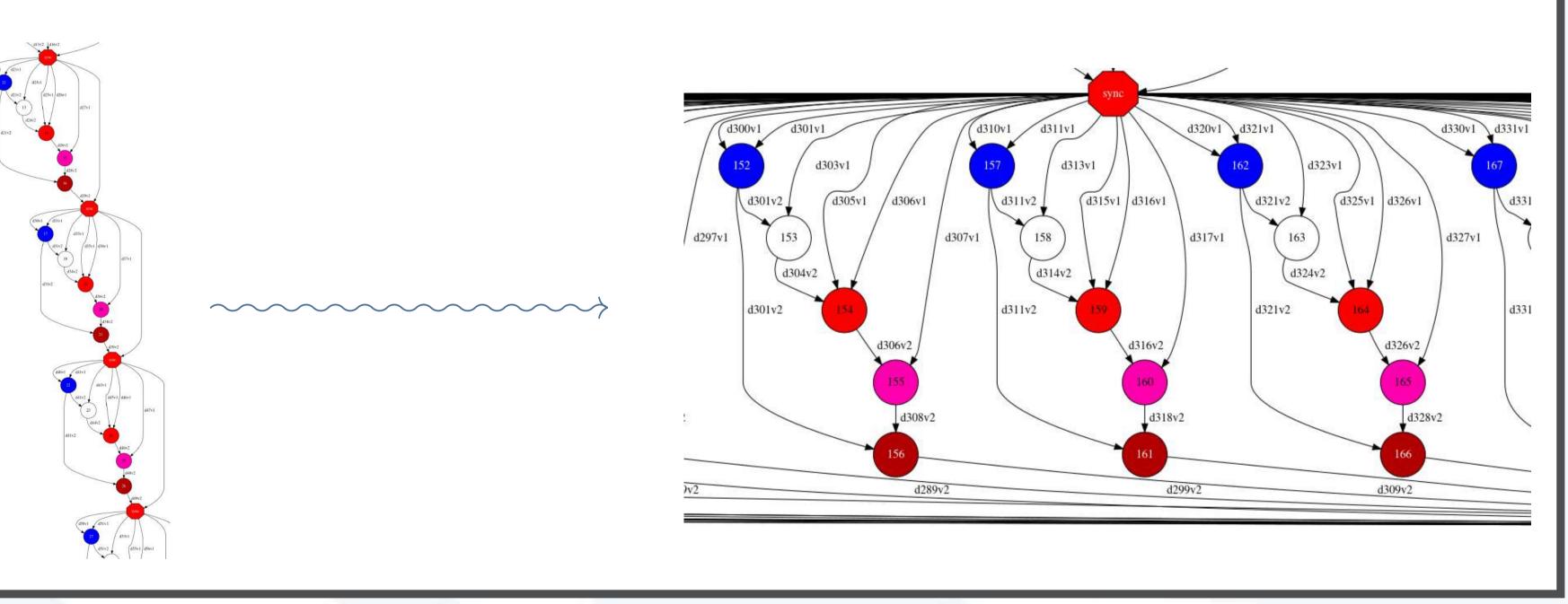
			Input Data	Encoded Data	T Reconstructed Da
Non-linear reduction:	AE	\longrightarrow		$u\left(\boldsymbol{\mu}\right) \approx f$	(g)

Note:

The non-linear reduction can achieve **smaller** solution manifolds with **better** accuracy.

5 - Parallel execution

Simultaneous execution of the same functions for multiple predictions or error calculations:



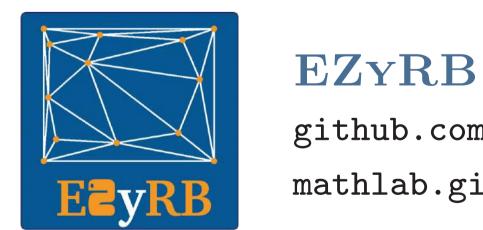
4 - Data parallelism

Input of large-sized batches from FOM:

- 1. Divide into mini-batches and distribute them across processing units.
- 2. Replicate the full model on each processing units to treat a minibatch.
- 3. Perform training locally and synchronise local gradients.
- 4. The **average** of the local gradients is used to **update** the local models.

aining Process Averaged Gradients Training Process Data Store Averaged Gradients Training Process Averaged Gradients Gradients 1. Read Data 3. Average Gradients

6 - Computational science and engineering softwares: mathlab.sissa.it/cse-software



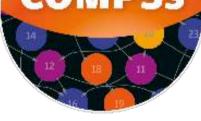






github.com/mathLab/EZyRB mathlab.github.io/EZyRB

EZyRB is a python library for data-driven (non-intrusive) model order reduction with linear and non-linear reduction and different approximation methods.



github.com/bsc-wdc/compss compss-doc.readthedocs.io/en/stable/index. html

COMPSs is a programming model to ease the development of applications for distributed infrastructures, such as Clusters, Clouds and Containerised Platforms.

github.com/deephealthproject/eddl deephealthproject.github.io/eddl/index.html

EDDL is an optimised tensor library for distributed deep learning with hardware transparency support for CPUs, GPUs and FPGAs.

References and Acknowledgements

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