

Stabilization techniques for pressure recovery applied to **POD-Galerkin** methods for the incompressible Navier-Stokes equations

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Introduction - 1

Motivations

- The numerical resolution of the **incompressible Navier-Stokes** equations is required in many different engineering fields and life sciences (e.g. aeronautical/naval/civil/mechanical/environmental engineering, hemodynamics.)
- When a large number of different system configurations are in need of being tested (e.g. uncertainty quantification, optimization) or a small computational cost is required (e.g. real-time control), the numerical resolution of the equations using standard high order discretization techniques (FEM-SEM-FVM-FDM) becomes not feasible. The development of efficient and reliable Reduced Order Models (ROMs) could be a great advantage.
- It is well known that Galerkin based ROMs of the incompressible Navier-Stokes

High Fidelity problem - 2

Governing Equations

The physical problem is modelled using the **unsteady incompressible Navier-Stokes** equations. The considered system of PDEs are the unsteady parametrized incom**pressible Navier Stokes Equations**. The space discretization of the equations has beed performed using a **finite volume** approach.

$$\begin{cases} \frac{\partial \boldsymbol{u}}{\partial t} + (\boldsymbol{u} \cdot \boldsymbol{\nabla})\boldsymbol{u} - \boldsymbol{\nabla} \cdot \boldsymbol{\nu} \boldsymbol{\nabla} \boldsymbol{u} = -\boldsymbol{\nabla} p & \text{in } \Omega \\ \boldsymbol{\nabla} \cdot \boldsymbol{u} = \boldsymbol{0} & \text{in } \Omega \\ \boldsymbol{u} = \overline{\boldsymbol{u}}(\mu) & \text{on } \partial\Omega_{,in} \\ \boldsymbol{u} = \boldsymbol{0} & \text{on } \partial\Omega_{,0} \\ (\boldsymbol{\nu} \nabla \boldsymbol{u} - p\boldsymbol{I})\boldsymbol{n} = 0 & \text{on } \partial\Omega_{,out} \end{cases}$$
(1)

equations suffer from stability issues for what concern the pressure term.

Examples of possible applications





Industrial Engineering Aeronautical Engineering Naval Engineering Methodology-Overview

Development and comparison of different stabilization techniques for the recovery of the pressure term in the contest POD-Galerkin ROMs of the incompressible Navier-Stokes equations. The developed methodology is based on the following flowchart:



The POD-Galerkin Dynamical system - 4

The Galerkin Projection

Performing a standard Galerkin projection of the governing equations onto the POD spaces of velocity and pressure and approximating the fields with the POD spaces one obtains:

$$\begin{cases} \dot{a} = \mu B a - a^T C a - K b \\ K^T a = 0 \end{cases}$$

Due to the **divergence-free** property of the velocity modes, the terms with red strikethrough are in most of the cases numerically zero so the resulting system suffer from stability issues. Normally only the first equation is solved and only the velocity field is recovered.

The Poisson equation for pressure

One possible way to reconstruct the pressure is to exploit a **Poisson equation for pressure** obtained taking the divergence of the momentum equation and exploiting the **divergence-free** constraint. The momentum equaton is then projected onto the POD velocity space and the Poisson equation for pressure is projected onto the POD pressure space:

$$\begin{cases} (\frac{\partial \boldsymbol{u}}{\partial t} + (\boldsymbol{u} \cdot \boldsymbol{\nabla})\boldsymbol{u} - \boldsymbol{\nabla} \cdot \boldsymbol{\nu}\boldsymbol{\nabla}\boldsymbol{u} + \boldsymbol{\nabla}\boldsymbol{p}, \boldsymbol{\phi})_{(L^{2}(\Omega))} = \boldsymbol{0} & \forall \boldsymbol{\phi} \in \mathbb{V}_{N_{u}} \\ (\boldsymbol{\Delta}\boldsymbol{p} + \boldsymbol{\nabla} \cdot ((\boldsymbol{u} \cdot \boldsymbol{\nabla})\boldsymbol{u}), \boldsymbol{\chi})_{(L^{2}(\Omega))} = \boldsymbol{0} & \forall \boldsymbol{\chi} \in \mathbb{Q}_{N_{p}} \end{cases}$$
(5)

• High Fidelity simulation of the physical problem trough the **finite volume** solver **OpenFOAM**^{(\mathbb{R})}. (**BOX 2**)

- Collection of the snapshots and construction of the reduced basis space \mathbb{V}_{rb} using a POD [1] approach. (BOX 3)
- Projection of the unsteady Navier-Stokes equation onto the reduced basis space \mathbb{V}_{rb} in order to construct the **POD-Galerkin dynamical system**. [2, 3]. (**BOX 4**)
- Development and comparison of different stabilization techniques for the pressure term. [4] (BOX 4)

Construction of \mathbb{V}_{rb} - 3

 $egin{array}{lll} \dot{m{a}} = m{B}m{a} - m{a}^Tm{C}m{a} - m{K}m{b} \ m{b} = m{D}^{-1}(m{a}^Tm{G}m{a}) \end{array}$

The Supremizer Stabilization

We know that in a Galerkin approach to ensure the solvability and stability of the problem the reduced basis spaces must fulfill the LBB parametrized **inf-sup** condition.

$$\inf_{q \in Q} \sup_{\boldsymbol{v} \in V} \frac{b(q, \boldsymbol{v}; \mu)}{\|q\|_Q \|v\|_V} = \beta(\mu) > 0 \quad (7) \qquad \qquad b(q, \boldsymbol{v}) = \int_{\Omega} q \nabla \cdot \boldsymbol{v} d\boldsymbol{x} \tag{8}$$

fulfil this condition at reduced order level a order supremizer to In **problem** is solved, and the velocity space is enriched with the additional modes obtained applying the POD onto the supremizer solutions.

$$\begin{cases} \Delta s = -\nabla p & \text{in } \Omega \\ s = \mathbf{0} & \text{on } \partial \Omega \end{cases} \quad (9) \quad \tilde{V}_u = \operatorname{span}\{\phi_1, ..., \phi_{N_u}\} \oplus \operatorname{span}\{\psi_1, ..., \psi_{N_s}\} \quad (10) \end{cases}$$

Results and Outlooks - 5

The methodology is tested studying the laminar flow (RE = 100) around a circular cylin-



dels					
		$arepsilon_U$	ε_p	comp. t	SU
	NO stab $(4\boldsymbol{\phi}, 4\boldsymbol{\chi})$	NaN	NaN	NaN	NaN
	NO stab $(4\boldsymbol{\phi})$	1.25%	-	1.80 s	823
	with sup. $(4\boldsymbol{\phi}, 4\boldsymbol{\chi}, 4\boldsymbol{s})$	1.95%	0.67%	$21.73 \mathrm{s}$	68
3640 3650	with PPE $(4\boldsymbol{\phi}, 4\boldsymbol{\chi})$	1.25%	0.51%	2.93 s	506

(6)

The reduced order space V_u and Q_p are constructed using a SVD on the snapshots matrices of **velocity** and **pressure**:

$$\mathcal{U}' = \mathcal{W}^{u} \Sigma^{u} \mathcal{V}^{uT}, \quad \mathcal{W}^{p} = [\phi_{1}, \phi_{2}, ..., \phi_{n}], \quad \Sigma_{ii}^{u} = \lambda_{i}^{u}$$
(2)
$$\mathcal{P} = \mathcal{W}^{p} \Sigma^{p} \mathcal{V}^{pT}, \quad \mathcal{W}^{p} = [\chi_{1}, \chi_{2}, ..., \chi_{n}], \quad \Sigma_{ii}^{p} = \lambda_{i}^{p}$$
(3)

We can **truncate** the dimension of the reduced basis space looking at the eigenvalues and we can finally construct the reduced basis spaces for the **Galerkin projection**:

 $\mathbb{V}_{N_u} = \operatorname{span}(\phi_1, \phi_2, ..., \phi_{N_u}) \qquad \qquad \mathbb{Q}_{N_p} = \operatorname{span}(\chi_1, \chi_2, ..., \chi_{N_p})$

Velocity Reconstruction HF, $t = 20\Delta t$ PPE, $t = 20\Delta t$ SUP, $t = 20\Delta t$







Pressure Reconstruction

Outlook

As future outlooks it would be interesting to test the presented methodologies for UQproblems, to investigate the stability for higher values of the Reynolds number and to test the stability for long time integrations.

References

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