## 13 Application: flow of Schrödinger equation

In this section we apply methods of pseudodifferential operators to prove several results on the flow of Schrödinger equation with unbounded coefficients.

### 13.1 Local smoothing effect

Consider the Cauchy problem

$$
\left\{\begin{array}{l}
\mathrm{i} \dot{u}=A u  \tag{13.1}\\
u(0)=u_{0}
\end{array}\right.
$$

where $A=\mathrm{Op}^{w}(a)$ has a real symbol $a(x, \xi) \in \mathcal{S}^{m}$, for instance $-\partial_{x_{j}}\left(a_{j k}(x) \partial_{x_{k}}\right)$, or $-\Delta$, or $\mathrm{i} \partial_{x}^{3}$. Since $A$ is selfadjoint, the operator $-\mathrm{i} A$ is skew-adjoint, hence the $L^{2}$ norm of the flow is preserved.

We want to prove the so called (local in time) local smoothing estimates, which says, roughly speaking, that the flow generated by $A$ locally in space regularize a bit the solution, provided one integrate over time. The classical smoothing estimate reads

$$
\begin{equation*}
\int_{0}^{T} \int_{|x| \leq R}\left|\langle D\rangle^{\frac{m-1}{2}} u(t, x)\right|^{2} \mathrm{~d} x \mathrm{~d} t \leq C_{T, R}\left\|u_{0}\right\|_{0}^{2} \tag{13.2}
\end{equation*}
$$

where the positive constant $C_{T, R}$ depends on $T, R$.
In particular inequality (13.2) implies that if $u_{0} \in L^{2}\left(\mathbb{R}^{d}\right)$ the solution $e^{-\mathrm{i} t A} u_{0} \in H_{\mathrm{loc}}^{\frac{m-1}{2}}$ for almost all $t$. Notice that this gain of derivatives is a pure dispersive phenomenon, which cannot hold in hyperbolic problems.

A very nice method of proof relies on the so called positive commutator method, which we now illustrate.
Let us take a bounded operator $B$, and consider the usual energy estimate, which reads

$$
\frac{\mathrm{d}}{\mathrm{~d} t}\langle B u, u\rangle=\left\langle\frac{1}{\mathrm{i}}[B, A] u, u\right\rangle=\langle\mathrm{i}[A, B] u, u\rangle
$$

as $-\mathrm{i} A$ is skew-adjoint. Integrating in time from 0 to $T$ and using that $B$ is bounded and the flow is unitary in $L^{2}$ we get

$$
\begin{equation*}
\int_{0}^{T}\langle\mathrm{i}[A, B] u, u\rangle \mathrm{d} t \leq C\left\|u_{0}\right\|_{0}^{2} \tag{13.3}
\end{equation*}
$$

Now the crucial point: choose $B$ such that $\mathrm{i}[A, B] \geq 0$ is positive.
Let us see some examples.
Case $A=-\Delta$. In this case we have the following result, due to Doi [?]:
Lemma 13.1 (Doi). Let $\lambda$ be even, radially decreasing, non negative, $\lambda \in L^{1}([0, \infty))$, smooth. Then there exists a real value symbol $b \in \mathcal{S}^{0}$ and a constant $0<\beta<1$ such that

$$
\left\{|\xi|^{2}, b\right\} \geq \beta \lambda(|x|)|\xi|-\frac{1}{\beta}
$$

Proof. Define $f(t):=\int_{0}^{t} \lambda(r) \mathrm{d} r$ and let

$$
\Phi(x)=\left(f\left(x_{1}\right), \ldots, f\left(x_{d}\right)\right)
$$

so that $\Phi(x)$ is smooth and bounded. Let

$$
\Phi_{\mathrm{sym}}^{\prime}(x):=\frac{1}{2}\left(\partial_{x_{j}} f_{i}+\partial_{x_{i}} f_{j}\right)=\left(\begin{array}{cccc}
\lambda\left(x_{1}\right) & 0 & \ldots & 0 \\
0 & \lambda\left(x_{2}\right) & \ldots & 0 \\
\vdots & \vdots & \ldots & \vdots \\
0 & 0 & \ldots & \lambda\left(x_{d}\right)
\end{array}\right) \geq \lambda(|x|) \mathrm{Id}
$$

as $\lambda$ is even and decreasing. Define

$$
b(x, \xi):=\Phi(x) \cdot \frac{\xi}{\langle\xi\rangle} \in \mathcal{S}^{0}
$$

Then

$$
\left\{|\xi|^{2}, b\right\}=2 \frac{\xi}{\langle\xi\rangle} \cdot \nabla_{x}(\Phi(x) \cdot \xi)=\frac{2}{\langle\xi\rangle} \Phi_{\mathrm{sym}}^{\prime}(x) \xi \cdot \xi \geq 2 \lambda(|x|) \frac{|\xi|^{2}}{\langle\xi\rangle}
$$

By Doi's lemma, we have that

$$
\{a, b\}_{\mathcal{M}}=\left\{|\xi|^{2}, b\right\}+r_{0} \geq \lambda(|x|)|\xi|-c_{0}
$$

and therefore by Garding inequality

$$
\langle\mathrm{i}[A, B] u, u\rangle \geq\left\langle\mathrm{Op}\left(\lambda(|x|)\langle\xi\rangle^{m-1}\right) u, u\right\rangle-c_{0}\|u\|_{0}^{2}-C\|u\|_{0}^{2}
$$

Finally use that

$$
\lambda(|x|)|\xi|=\sqrt{\lambda(|x|)|\xi|} \sqrt{\lambda(|x|)|\xi|}=(\sqrt{\lambda(|x|)|\xi|})^{*} \# \sqrt{\lambda(|x|)|\xi|}+\mathcal{S}^{0}
$$

so that

$$
\left\langle\operatorname{Op}\left(\lambda(|x|)\langle\xi\rangle^{m-1}\right) u, u\right\rangle=\left\|\operatorname{Op}\left(\lambda(|x|)^{\frac{1}{2}}|\xi|^{\frac{1}{2}}\right) u\right\|_{0}^{2}-\langle\operatorname{Op}(r) u, u\rangle, \quad r \in \mathcal{S}^{0}
$$

Altogether we have proved that

$$
\int_{0}^{T}\left\|\mathrm{Op}\left(\lambda(|x|)^{\frac{1}{2}}|\xi|^{\frac{1}{2}}\right) u\right\|_{0}^{2} \mathrm{~d} t \leq C_{T}\left\|u_{0}\right\|_{0}^{2}
$$

which is the smoothing effect.
Case $A=-\partial_{x_{j}}\left(a_{j k}(x) \partial_{x_{k}}\right.$. The proof is analogous to the previous one. In this case, so get the analogous statement than Lemma 13.2, one needs to require that
(H1) $A(x)=\left(a_{j k}(x)\right)$ is real, symmetric and positive definite.
(H2) $a_{j k} \in C_{b}^{\infty}$ and

$$
\left|\nabla a_{j k}(x)\right|=o\left(|x|^{-1}\right), \quad x \rightarrow \infty
$$

(H3) the Hamiltonian flow of $A(x) \xi \cdot \xi$ is non trapped in one direction, i.e. the orbits of the hamiltonian system with hamiltonian $A(x) \xi \cdot \xi$ are unbounded for any initial datum.

Under these conditions, Doi [?] proved that Lemma 13.2 is true with $A(x) \xi \cdot \xi$ replacing $|\xi|^{2}$.

### 13.2 Cauchy theory for non-selfadjoint perturbation

Consider the Schrödinger equation

$$
\mathrm{i} \dot{u}=-\Delta u+b(x) \cdot \partial_{x} u+c(x) u
$$

where $b(x)=\left(b_{1}(x), \ldots, b_{d}(x)\right) \in C^{\infty}\left(\mathbb{R}^{d}, \mathbb{C}^{d}\right)$ with

$$
\left|\partial_{x}^{\alpha} b_{j}(x)\right| \leq C_{\alpha} \quad \forall \alpha, \quad \forall j=1, \ldots, d
$$

The difficult is that $b$ might have a real part, and the perturbation $\operatorname{Re} b \partial_{x}$ is bad in an energy estimate.

We assume that $\operatorname{Re} b(x)$ decrease when $x \rightarrow \infty$, and in particular that

$$
\begin{equation*}
|\operatorname{Re} b(x)| \leq \frac{C}{\langle x\rangle^{2}} \tag{13.4}
\end{equation*}
$$

Let us see why.
First we write the operator using Weyl quantization (it is useful because the adjoint are much easier to compute!) We have that

$$
\begin{array}{r}
-\Delta=\mathrm{Op}^{w}\left(|\xi|^{2}\right) \\
b(x) \partial_{x}=\mathrm{Op}(b \mathrm{i} \xi)=\mathrm{Op}^{w}\left(\mathrm{i} b(x) \cdot \xi-\frac{1}{2} \nabla_{x} b\right) \\
c(x)=\mathrm{Op}^{w}(c)
\end{array}
$$

where we used the change of quantization formula $\mathrm{Op}(f)=\mathrm{Op}^{w}(g)$ with

$$
g \sim \sum_{\alpha}\left(-\frac{1}{2}\right)^{|\alpha|} \frac{1}{\alpha!} \partial_{\xi}^{\alpha} D_{x}^{\alpha} f .
$$

Hence we rewrite the equation in decreasing order as

$$
\begin{equation*}
\mathrm{i} \dot{u}=\mathrm{Op}^{w}\left(|\xi|^{2}\right) u+\mathrm{Op}^{w}(\mathrm{i} b(x) \cdot \xi) u+\mathrm{Op}^{w}\left(c_{0}\right) u, \quad c_{0} \in \mathcal{S}^{0} . \tag{13.5}
\end{equation*}
$$

Let us make an energy estimate in $H^{s}$ : if

$$
A:=\frac{1}{\mathrm{i}} \mathrm{Op}^{w}\left(|\xi|^{2}+\mathrm{i} b(x) \cdot \xi+c_{0}\right),
$$

we have that

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} t}\left\langle\langle D\rangle^{2 s} u, u\right\rangle=\left\langle\left(A+A^{*}\right)\langle D\rangle^{2 s} u, u\right\rangle+\left\langle\left[\langle D\rangle^{2 s}, A\right] u, u\right\rangle . \tag{13.6}
\end{equation*}
$$

We need to bound the two terms in $H^{s}$. We start with the second one, which does not create problems. Indeed

$$
\begin{aligned}
{\left[\langle D\rangle^{2 s}, A\right] } & =\frac{1}{\mathrm{i}}\left[\langle D\rangle^{2 s}, \mathrm{Op}^{w}\left(|\xi|^{2}+b(x) \mathrm{i} \xi+c-\frac{1}{2} b_{x}\right)\right] \\
& =\frac{1}{\mathrm{i}}\left[\langle D\rangle^{2 s}, \mathrm{Op}^{w}\left(\mathrm{i} b(x) \cdot \xi+c_{0}\right)\right] \in \mathrm{Op}^{w}\left(S^{2 s}\right)
\end{aligned}
$$

hence $\left[\langle D\rangle^{2 s}, A\right]$ is good in an energy estimate:

$$
\left|\left\langle\left[\langle D\rangle^{2 s}, A\right] u, u\right\rangle\right| \leq\left\|\left[\langle D\rangle^{2 s}, A\right] u\right\|_{-s}\|u\|_{s} \leq C_{s}\|u\|_{s}^{2}
$$

The other term in (13.6) is worse. Let us compute it:

$$
\begin{aligned}
A+A^{*} & =\frac{1}{\mathrm{i}} \mathrm{Op}^{w}\left(|\xi|^{2}+\mathrm{i} b(x) \cdot \xi+c_{0}\right)-\frac{1}{\mathrm{i}} \mathrm{Op}^{w}\left(|\xi|^{2}-\mathrm{i} \bar{b}(x) \cdot \xi+\bar{c}_{0}\right) \\
& =\mathrm{Op}^{w}\left((b+\bar{b}) \cdot \xi+c_{1}\right), \quad c_{1} \in \mathcal{S}^{0} \\
& =\mathrm{Op}^{w}(2(\operatorname{Re} b) \cdot \xi)+\mathrm{Op}^{w}\left(c_{1}\right)
\end{aligned}
$$

The first term is a problem in an energy estimate!! We have too many derivatives. Indeed we cannot bound

$$
\left|\left\langle\left(A+A^{*}\right)\langle D\rangle^{2 s} u, u\right\rangle\right| \leq C_{s}\|u\|_{s}^{2}
$$

because the term $\mathrm{Op}^{w}(2(\operatorname{Re} b) \cdot \xi)\langle D\rangle^{2 s} \in \mathrm{Op}\left(\mathcal{S}^{2 s+1}\right)$ and we cannot close the energy estimate.
We do not surrender: can we make a change of coordinates which "simplify the term"?
So we look for a change of coordinates of the form

$$
\varphi=\mathcal{U}(1,0) u
$$

where $\mathcal{U}(1,0)$ is the time 1 flow of the PDE generated by a pseudodifferential operator $X=\mathrm{Op}(\chi)$

$$
\dot{u}=X u
$$

with $\chi \in \mathcal{S}^{0}$ to be determined later on. Note that $\mathcal{U}(1,0)$ is invertible and maps $H^{s} \rightarrow H^{s} \forall s$. Thus if we prove good estimates for $\varphi$, they hold also for $u$.

Then $\varphi$ fulfills the equation

$$
\mathrm{i} \dot{\varphi}=\mathcal{U}(1,0) \mathrm{Op}^{w}\left(|\xi|^{2}+\mathrm{i} b(x) \cdot \xi+c_{0}\right) \mathcal{U}(1,0)^{-1} \varphi .
$$

Decompose

$$
\begin{aligned}
\mathcal{U}(1,0) \mathrm{Op}^{w}\left(|\xi|^{2}+\mathrm{i} b(x) \cdot \xi+c_{0}\right) \mathcal{U}(1,0)^{-1} & =\mathcal{U}(1,0) \mathrm{Op}^{w}\left(|\xi|^{2}\right) \mathcal{U}(1,0)^{-1} \\
& +\mathcal{U}(1,0) \mathrm{Op}^{w}(\mathrm{i} b(x) \cdot \xi) \mathcal{U}(1,0)^{-1} \\
& +\mathcal{U}(1,0) \mathrm{Op}^{w}\left(c_{0}\right) \mathcal{U}(1,0)^{-1}
\end{aligned}
$$

We expand each line in decreasing order:

$$
\begin{aligned}
& \mathcal{U}(1,0) \mathrm{Op}^{w}\left(|\xi|^{2}\right) \mathcal{U}(1,0)^{-1}=\mathrm{Op}^{w}\left(|\xi|^{2}\right)+\left[X, \mathrm{Op}^{w}\left(|\xi|^{2}\right)\right]+R_{0} \\
& \mathcal{U}(1,0) \mathrm{Op}^{w}(\mathrm{i} b(x) \cdot \xi) \mathcal{U}(1,0)^{-1}=\mathrm{Op}^{w}(\mathrm{i} b(x) \cdot \xi)+R_{0} \\
& \mathcal{U}(1,0) \mathrm{Op}^{w}\left(c_{0}\right) \mathcal{U}(1,0)^{-1}=R_{0}
\end{aligned}
$$

where $R_{0}$ is a bounded operator from $H^{s} \rightarrow H^{s}, \forall s$. Collecting the terms of the same order we find that

$$
\mathrm{i} \dot{\varphi}=H \varphi
$$

with

$$
\begin{aligned}
H:= & \mathrm{Op}^{w}\left(|\xi|^{2}\right) \\
& +\left[X, \mathrm{Op}^{w}\left(|\xi|^{2}\right)\right]+\mathrm{Op}^{w}(\mathrm{i} \operatorname{Re} b(x) \cdot \xi)-\mathrm{Op}^{w}(\operatorname{Im} b(x) \cdot \xi) \\
& +R_{0}
\end{aligned}
$$

Now $\mathrm{Op}^{w}(\operatorname{Im} b(x) \cdot \xi)$ is selfdjoint, so it does not give us problems in an energy estimate. On the contrary, as we have seen, $\mathrm{Op}^{w}(\operatorname{iRe} b(x) \cdot \xi)$ is problematic and we would like to eliminate it.

We distinguish two cases.
Case $d=1$. In case the dimension $d=1$, we can find $X$ to eliminate the bad part. Namely we look for $X=\mathrm{Op}^{w}(\chi)$ such that

$$
\left[X, \mathrm{Op}^{w}\left(|\xi|^{2}\right)\right]+\mathrm{Op}^{w}(\mathrm{i} \operatorname{Re} b(x) \cdot \xi)=Z_{0}, \quad Z_{0} \in \mathrm{Op}^{w}\left(\mathcal{S}^{0}\right)
$$

By symbolic calculus, it is enough to choose $X=\mathrm{Op}^{w}(\chi)$ such that

$$
\left\{\begin{array}{l}
-\mathrm{i}\left\{\chi, \xi^{2}\right\}+\mathrm{i} \operatorname{Re} b(x) \xi=0 \\
z_{0}=-\mathrm{i}\left(\left\{\chi, \xi^{2}\right\}_{M}-\left\{\chi, \xi^{2}\right\}\right) \in \mathcal{S}^{0}, \quad Z_{0}:=\mathrm{Op}^{w}\left(z_{0}\right)
\end{array}\right.
$$

The first equation is

$$
\left\{\xi^{2}, \chi\right\}+\operatorname{Re} b(x) \xi=0
$$

namely

$$
2 \xi \chi_{x}+\operatorname{Re} b(x) \xi=0 \Rightarrow 2 \chi_{x}+\operatorname{Re} b(x)=0
$$

which is solved by

$$
\chi(x)=\int_{0}^{x} \operatorname{Re} b(y) \mathrm{d} y
$$

The assumption (13.4) guarantees that $\chi \in C^{\infty} \cap L^{\infty}$. It follows that $\chi \in \mathcal{S}^{0}$ is a symbol and our construction work!
With this choice, we have that $\varphi$ fulfills

$$
\mathrm{i} \dot{\varphi}=\left(\mathrm{Op}^{w}\left(|\xi|^{2}\right)-\mathrm{Op}^{w}(\operatorname{Im} b(x) \cdot \xi)+R_{0}\right) \varphi
$$

hence it fulfills good energy estimates and we can prove that

$$
\partial_{t}\|\varphi(t)\|_{s}^{2} \leq C_{s}\|\varphi\|_{s}^{2} \quad \Rightarrow \quad\|\varphi(t)\|_{s} \leq e^{t C_{s}}\|\varphi(0)\|_{s}
$$

Case $d \geq 2$. In this case the homological equation is more complicated, being

$$
\left\{|\xi|^{2}, \chi\right\}+\operatorname{Re} b(x) \cdot \xi=0
$$

and we cannot solve it exactly (it is a PDEs in $\chi$ ). However, we can impose the weaker condition which is sufficient for our aim. Indeed it is enough to impose a sign condition. This will be done using Doi lemma
Lemma 13.2 (Doi). Let $\lambda$ be even, smooth, radially decreasing, non negative, $\lambda \in L^{1}([0, \infty))$. Then there exists a real value symbol $p \in \mathcal{S}^{0}$ and a constant $\beta>0$ such that

$$
\left\{|\xi|^{2}, p\right\} \geq \lambda(|x|)|\xi|-\beta
$$

Proof. Define $f(t):=\int_{0}^{t} \lambda(r) \mathrm{d} r$ and let

$$
\Phi(x)=\left(f\left(x_{1}\right), \ldots, f\left(x_{d}\right)\right)
$$

so that $\Phi(x)$ is smooth and bounded. Let

$$
\Phi_{\mathrm{sym}}^{\prime}(x):=\frac{1}{2}\left(\partial_{x_{j}} f_{i}+\partial_{x_{i}} f_{j}\right)=\left(\begin{array}{cccc}
\lambda\left(x_{1}\right) & 0 & \ldots & 0 \\
0 & \lambda\left(x_{2}\right) & \ldots & 0 \\
\vdots & \vdots & \ldots & \vdots \\
0 & 0 & \ldots & \lambda\left(x_{d}\right)
\end{array}\right) \geq \lambda(|x|) \mathrm{Id}
$$

as $\lambda$ is even and decreasing. Define

$$
p(x, \xi):=\Phi(x) \cdot \frac{\xi}{\langle\xi\rangle} \in \mathcal{S}^{0} .
$$

Then

$$
\left\{|\xi|^{2}, p\right\}=2 \frac{\xi}{\langle\xi\rangle} \cdot \nabla_{x}(\Phi(x) \cdot \xi)=\frac{2}{\langle\xi\rangle} \Phi_{\mathrm{sym}}^{\prime}(x) \xi \cdot \xi \geq 2 \lambda(|x|) \frac{|\xi|^{2}}{\langle\xi\rangle} \geq \lambda(|x|)|\xi|-\beta
$$

for some $\beta>0$.
We exploit Doi Lemma. We choose $\lambda(t)=\langle t\rangle^{-2}$, and select $p \in \mathcal{S}^{0}$ so that

$$
\left\{|\xi|^{2}, p\right\} \geq \frac{|\xi|}{\langle | x| \rangle^{2}}-\beta
$$

Then we put

$$
\chi:=-2 p \in \mathcal{S}^{0}
$$

so that in the homological equation

$$
\left\{|\xi|^{2}, \chi\right\}+\operatorname{Re} b(x) \cdot \xi=-2\left\{|\xi|^{2}, p\right\}+\operatorname{Re} b(x) \cdot \xi \leq-2 \frac{|\xi|}{\langle x\rangle^{2}}+\beta+\frac{|\xi|}{\langle x\rangle^{2}} \leq-\frac{|\xi|}{\langle x\rangle^{2}}+\beta
$$

Thus the homological equation has a sign. Let's see how to use it!
Let us now perform an energy estimate. We have that

$$
\frac{\mathrm{d}}{\mathrm{~d} t}\left\langle\langle D\rangle^{2 s} \varphi, \varphi\right\rangle=\left\langle\left(\frac{1}{\mathrm{i}}\left(H-H^{*}\right)\langle D\rangle^{2 s} u, u\right\rangle+\left\langle\left[\langle D\rangle^{2 s}, \frac{1}{\mathrm{i}} H\right] \varphi, \varphi\right\rangle .\right.
$$

The second term has good estimate, as before. Concerning the first term we have (as $\chi$ is real valued)

$$
\begin{aligned}
\frac{1}{\mathrm{i}}\left(H-H^{*}\right) & =\frac{2}{\mathrm{i}}\left[X, \mathrm{Op}^{w}\left(|\xi|^{2}\right)\right]+2 \mathrm{Op}^{w}(\operatorname{Re} b(x) \cdot \xi) \\
& =2 \mathrm{Op}^{w}\left(\left\{|\xi|^{2}, \chi\right\}+\operatorname{Re} b(x) \cdot \xi\right)+\mathrm{Op}^{w}\left(r_{0}\right)
\end{aligned}
$$

Hence, againg by symbolic calculus

$$
\left\langle\left(\frac{1}{\mathrm{i}}\left(H-H^{*}\right)\langle D\rangle^{2 s} u, u\right\rangle=\left\langle\mathrm{Op}^{w}\left(\left(\left\{|\xi|^{2}, \chi\right\}+\operatorname{Re} b(x) \cdot \xi\right)\langle\xi\rangle^{2 s}\right) u, u\right\rangle+\left\langle\mathrm{Op}^{w}\left(r_{2 s}\right) u, u\right\rangle\right.
$$

Note that the last term fulfill energy estimates, so it is ok. Concerning the first one, we have that its symbol fulfills

$$
g(x, \xi):=\left(\left\{|\xi|^{2}, \chi\right\}+\operatorname{Re} b(x) \cdot \xi\right)\langle\xi\rangle^{2 s} \leq-\frac{|\xi|\langle\xi\rangle^{2 s}}{\langle x\rangle^{2}}+\beta\langle\xi\rangle^{2 s}
$$

and by the strong Garding inequality

$$
\left\langle\mathrm{Op}^{w}(g) u, u\right\rangle \leq-\left\langle\mathrm{Op}\left(\langle x\rangle^{-2}|\xi|\langle\xi\rangle^{2 s}\right) u, u\right\rangle+C\|u\|_{s}^{2} .
$$

Finally use that

$$
\langle x\rangle^{-2}|\xi|\langle\xi\rangle^{2 s}=\left(\sqrt{\langle x\rangle^{-2}|\xi|\langle\xi\rangle^{2 s}}\right)^{2}=\left(\sqrt{\langle x\rangle^{-2}|\xi|\langle\xi\rangle^{2 s}}\right)^{*} \# \sqrt{\langle x\rangle^{-2}|\xi|\langle\xi\rangle^{2 s}}+\mathcal{S}^{2 s}
$$

so that

$$
\left\langle\mathrm{Op}\left(\langle x\rangle^{-2}|\xi|\langle\xi\rangle^{2 s}\right) \varphi, \varphi\right\rangle=\left\|\mathrm{Op}\left(\sqrt{\langle x\rangle^{-2}|\xi|\langle\xi\rangle^{2 s}}\right) \varphi\right\|_{0}^{2}+\left\langle\mathrm{Op}\left(r_{2 s}\right) \varphi, \varphi\right\rangle, \quad r_{2 s} \in \mathcal{S}^{2 s}
$$

In this way the energy estimate becomes

$$
\frac{\mathrm{d}}{\mathrm{~d} t}\|\varphi\|_{s}^{2} \leq-\left\|\mathrm{Op}\left(\sqrt{\langle x\rangle^{-2}|\xi|\langle\xi\rangle^{2 s}}\right) \varphi\right\|_{0}^{2}+C\|\varphi\|_{s}^{2}
$$

namely

$$
\|\varphi(t)\|_{s}^{2}+\int_{0}^{t}\left\|\mathrm{Op}\left(\sqrt{\langle x\rangle^{-2}|\xi|\langle\xi\rangle^{2 s}}\right) \varphi(\tau)\right\|_{0}^{2} \mathrm{~d} \tau \leq\|\varphi(0)\|_{s}^{2}+C \int_{0}^{t}\|\varphi(\tau)\|_{s}^{2} \mathrm{~d} \tau
$$

hence we control the $H^{s}$ norm!!
Case of variable coefficients at highest order We can also consider the case where the PDEs is with variable coefficients at highest order, namely

$$
\mathrm{i} \dot{u}=-\left(\sum_{j, k} \partial_{x_{k}} a_{j k}(x) \partial_{x_{j}}\right) u+b(x) \cdot \partial_{x} u+c(x) u
$$

In this case we make the following assumptions
(H1) $a_{j, k}(x), b(x), c(x) \in \mathcal{S}^{0}$ (namely smooth, bounded with bounded derivatives), and $\left(a_{j, k}(x)\right)_{j, k}$ symmetric and real.
(H2) ellipticity at highest order

$$
\delta^{-1}|\xi|^{2} \leq \sum_{a_{j, k}(x) \xi_{j} \xi_{k}} \leq \delta|\xi|^{2}
$$

(H3) asymptotic flatness at infinity

$$
\left|\partial_{x}^{\alpha}\left(a_{j k}(x)-1\right)\right| \leq \frac{C}{\langle x\rangle^{2}}, \quad \forall j, k, \quad \forall \alpha \in \mathbb{N}^{d}
$$

Also in this case we can prove that the solution exists in $H^{s}$.
Case $d=1$. Let us put in dimension 1 first. Then

$$
\partial_{x}\left(a(x) \partial_{x}\right) u=a(x) \partial_{x x} u+a_{x}(x) \partial_{x} u
$$

so we write the equation as

$$
\mathrm{i} \dot{u}=-a(x) \partial_{x x} u+\left(b(x)+a_{x}\right) \partial_{x} u+c(x) u
$$

Let us put the coefficient at highest order to constant coefficient. This can be done with Egorov theorem, but in this case it is easier to perform a direct computation: let us make the change of variables

$$
u(x)=v(x+\beta(x))
$$

with $\beta(x)$ to be determined in such a way that $y=x+\beta(x)$ is a diffeomorphism. Then

$$
\begin{array}{r}
\partial_{x} u=\left(\partial_{x} v\right)(x+\beta(x))\left(1+\beta_{x}(x)\right) \\
\partial_{x x} u=\left(\partial_{x x} v\right)(x+\beta(x))\left(1+\beta_{x}(x)\right)^{2}+\left(\partial_{x} v\right)(x+\beta(x)) \beta_{x x}(x)
\end{array}
$$

So writing the direct and inverse diffeomorphism

$$
y=x+\beta(x), \quad x=y+\breve{\beta}(y)
$$

we find for $v$ the equation

$$
\mathrm{i} \dot{v}=-\left[a\left(1+\beta_{x}\right)^{2}\right]_{y+\breve{\beta}(y)} \partial_{y y} v+\left[\beta_{x x}+\left(1+\beta_{x}\right)\left(b+a_{x}\right)\right]_{y+\breve{\beta}(y)} \partial_{y} v+c_{y+\breve{\beta}(y)} v
$$

Now we look for $\beta$ so that

$$
a\left(1+\beta_{x}\right)^{2}=1
$$

As the ellipticity assumption in this case gives $a(x) \geq \delta^{-1}>0$, we have

$$
\beta_{x}=\sqrt{\frac{1}{a}}-1=\frac{1-a}{a+\sqrt{a}}
$$

and integrating

$$
\beta(x)=\int_{0}^{x} \frac{1-a(y)}{a(y)+\sqrt{a(y)}} \mathrm{d} y
$$

Now assumption (H2) gives that $|a(x)-1|=O\left(\langle x\rangle^{-2}\right)$, hence $\beta(x)$ is bounded. Moreover as

$$
1+\beta_{x}=\sqrt{\frac{1}{a}} \geq \delta^{-1 / 2}>0
$$

the function $x+\beta(x)$ is a good diffeomorphism.
With this choice we have

$$
\mathrm{i} \dot{v}=-\partial_{y y} v+\tilde{b}(y) \partial_{y} v+\tilde{c} v
$$

with

$$
\tilde{b}(y):=\left[\beta_{x x}+\left(1+\beta_{x}\right)\left(b+a_{x}\right)\right]_{y+\breve{\beta}(y)}
$$

Then one verifies, using the properties of $\beta(x)$ and the assumptions, that the new coefficient $\tilde{b}$ fulfills

$$
|\operatorname{Re} \tilde{b}(y)| \lesssim\langle y\rangle^{-2}
$$

Hence we are in the previous case.

