

# Regularity of solutions to Hamilton-Jacobi, Hyperbolic Conservation Laws and Monge transportation problem

L. Caravenna, C. De Lellis, M. Gloyer, R. Robyr, S. B.

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## Introduction

What kind of regularity

Precise statements

## Transport along rays

Area estimate

Disintegration

Reformulation of transport equation

Optimal transport on manifolds

Geodesic spaces

## SBV estimates for HJ and HCL

A formula for the divergence

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# Outline

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# Structure of solutions to Hamilton-Jacobi

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$$u_t + H(\nabla u) = 0, \quad (t, x) \in \mathbb{R}^+ \times \mathbb{R}^m,$$

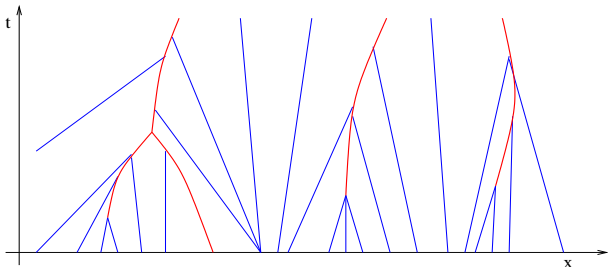
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with uniformly convex Hamiltonian  $H$  and Lipschitz initial data. We expect a smooth function outside countably many regular hypersurfaces of codimension 1.



# Structure of solutions to Hyperbolic conservation laws

For strictly hyperbolic system of conservation laws in one space dimension

$$u_t + f(u)_x = 0, \quad (t, x) \in \mathbb{R}^+ \times \mathbb{R}, \quad u \in \mathbb{R}^m,$$

one can decompose the derivative  $u_x$  in waves

$$u_x = \sum_i v_i \tilde{r}_i, \quad u_t = \sum_i w_i \tilde{r}_i,$$

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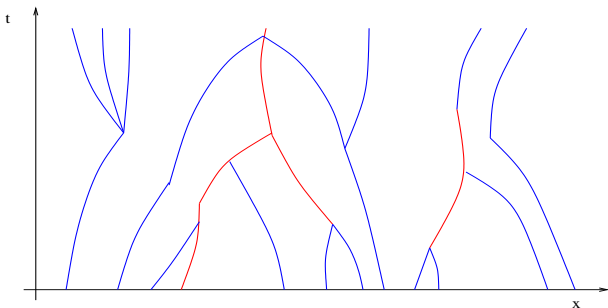
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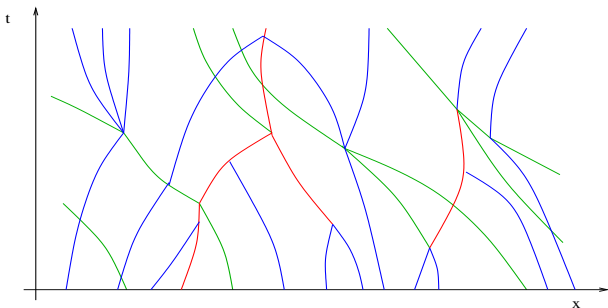
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3. the continuous part of  $v_i$  satisfies the equation

$$(v_i)_t + (\lambda_i v_i)_x = J_i, \quad J_i \in \mathcal{M}(\mathbb{R}^+ \times \mathbb{R}).$$

Hence each  $v_i$  should have a similar structure to the second derivative of the solution to a Hamilton-Jacobi equation, but the functions  $\lambda_i$  depends on  $u$  and there is a source  $J_i$ .



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The first question is an easy application of a well known rectifiability criteria.



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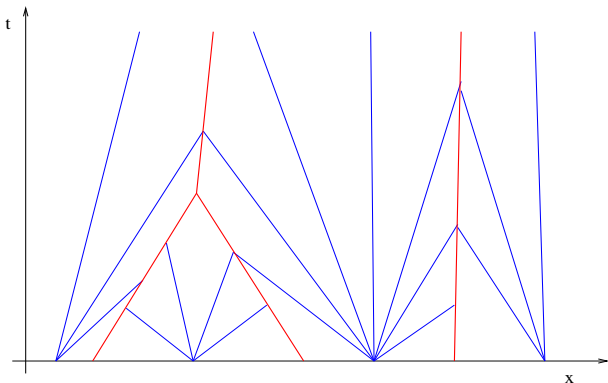
is given by

$$u(t, x) = \min_y \left\{ u(0, y) + tL\left(\frac{x - y}{t}\right) \right\}, \quad L = H^*.$$

In particular, it is uniformly approximated by the sequence of functions

$$u_n(t, x) = \min \left\{ u(0, y) + tL\left(\frac{x - y}{t}\right), y \in \{y_1, \dots, y_n\} \right\}. \quad (1)$$

These solutions have a very simple structure:



In particular, we have the estimates:

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By (1), one can show that this is the worst case, i.e.

$$c(t, s, x) \begin{cases} \leq \left( \frac{t-s}{t} \right)^m & t \leq s \\ \geq \left( \frac{t-s}{t} \right)^m & t \geq s \end{cases}$$

Since along optimal rays we have the dual solution

$$u(s, x) = \max \left\{ u(t, y) - (t - s)L\left(\frac{y - x}{t - s}\right) \right\},$$

we obtain the bound on the Jacobian

$$\min \left\{ \left(\frac{t - s}{t}\right)^m, \left(\frac{T - s}{T - t}\right)^m \right\} \leq c \leq \max \left\{ \left(\frac{t - s}{t}\right)^m, \left(\frac{T - s}{T - t}\right)^m \right\},$$

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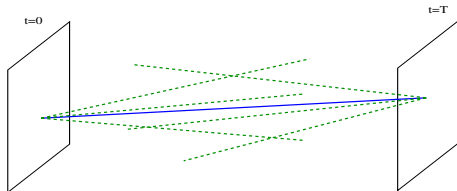
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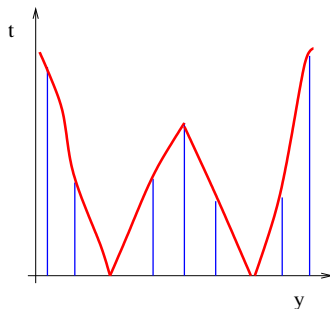
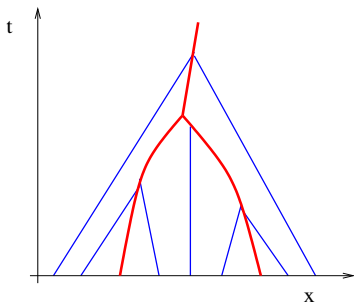


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The above estimate implies that the change of variable

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$$\mathcal{L}_{\mathbb{R}^+ \times \mathbb{R}^m}^{d+1} = \int c(t, y) dt m(dy),$$

i.e.  $\forall \phi \in C^c(\mathbb{R}^+ \times \mathbb{R}^m)$

$$\int \phi \mathcal{L}^{d+1} = \int \left( \int \phi(t, y + td(y)) c(t, y) dt \right) m(dy).$$

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**Remark.** The proof depends only on the convexity of  $H$ .

## Riemannian manifolds

Instead of the cost  $\|\cdot\|$ , we can use the distance cost on a Riemannian manifold  $(M, m)$

$$d(x, y) = \inf \left\{ \int_0^1 \sqrt{m_{ij}(\gamma(t)) \dot{\gamma}^i(t) \dot{\gamma}^j(t)} dt, \gamma(0) = x, \gamma(1) = y \right\}.$$

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In the smooth case, the study of the evolution of the Jacobian  $J$  reduces to the system

$$\begin{cases} \dot{J} &= UJ \\ \dot{U} &= -U^2 - R(\dot{\gamma}, \dot{\gamma}) \end{cases}$$

where  $R$  is a symmetric tensor whose trace is Ric.

In particular, if  $JJ^{-1}(0)$  is symmetric (ok for optimal transportation where a potential is present) we obtain that  $\det J$  satisfies

$$\frac{d^2}{dt^2} \log \det J \leq -\text{Ric}(\dot{\gamma}, \dot{\gamma}),$$

so that if the Ricci curvature is bounded from below, the function

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Hence if the two measures  $\mu, \nu$  are absolutely continuous, the Jacobian never vanishes and we obtain again an absolutely continuous disintegration along rays:

$$\frac{d^2}{dt^2} \log c(t, y) = \frac{d^2}{dt^2} \log \left( \frac{1}{\det J} \right) \geq \text{Ric}(\dot{\gamma}, \dot{\gamma}).$$

## General geodesic spaces

The semiconvexity estimate is stable under a weak convergence notion of metric spaces. Recall that a geodesic space is a metric space  $(X, d_L)$  such that

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The space is non-branching if the geodesics do not split.

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### Definition

$(X, d, d_L, \eta)$  is a *measure geodesic space* if  $(X, d)$  is a Polish space,  $(X, d_L)$  is a geodesic space with  $d_L : X \times X \rightarrow [0, +\infty]$   $d$ -l.s.c., and  $\eta$  is a probability measure on  $(X, d)$ .

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It can be shown that under this convergence Ricci bounds are preserved.

**Example.** The optimal transport in Wiener space is equivalent to the optimal transport in

$$\left( \ell^2, \|\cdot\|_{\ell^2}, \|\cdot\|_{h^1}, \prod_i \frac{i}{\sqrt{\pi}} e^{-i^2 x_i^2} dx_i \right),$$

and it is possible to show that the curvature is 1 (Sturm).

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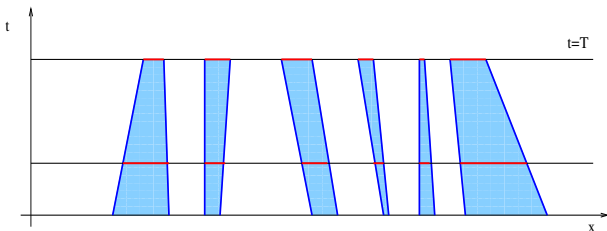
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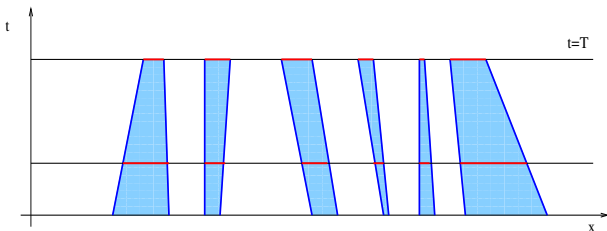




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In particular, if there is a Cantor part (hence single rays), the area is strictly positive.

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Since  $\operatorname{div} d(t, x) = \operatorname{tr}(D^2 H(\nabla u) D^2 u)$ ,  $D^2 H \geq c\mathbb{I}$  and  $D^2 u \leq 0$  in the Cantorian part, we obtain that  $\operatorname{tr}(D^2 u)$  has not Cantor parts, hence  $D^2 u$  has not Cantor parts.

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2. equation for  $v_i^s$ :

$$(v_i^s)_t + (\tilde{\lambda}_i v_i^s)_x = J_i^s,$$

$$|J_i^s|((s, t] \times \mathbb{R}) \leq \text{Tot. Var.}(v_i - v_i^s(s)) - \text{Tot. Var.}(v_i - v_i^s(t)) \\ + C(Q(s) - Q(t)).$$

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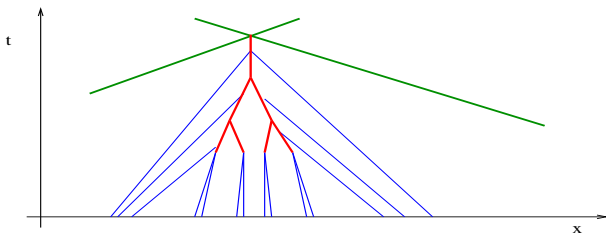
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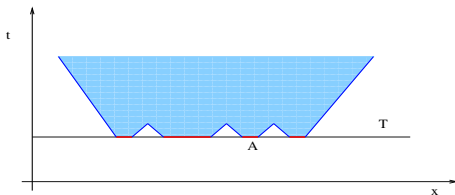
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As argument similar to the estimate of the decay of positive waves yields now

$$v_i^c(T, A) \geq -\frac{\mathcal{L}^1(A)}{t - T} - |J_i^c| \left( \text{Domain of influence of } A \right).$$





In particular, if  $A$  is a set of measure 0 where the Cantor part is concentrated, then by taking a sequence  $t_n \searrow T$  we obtain

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These times corresponds to:

1. strong interactions among waves;
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# Outline

Introduction

Transport along rays

SBV estimates for HJ and HCL

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