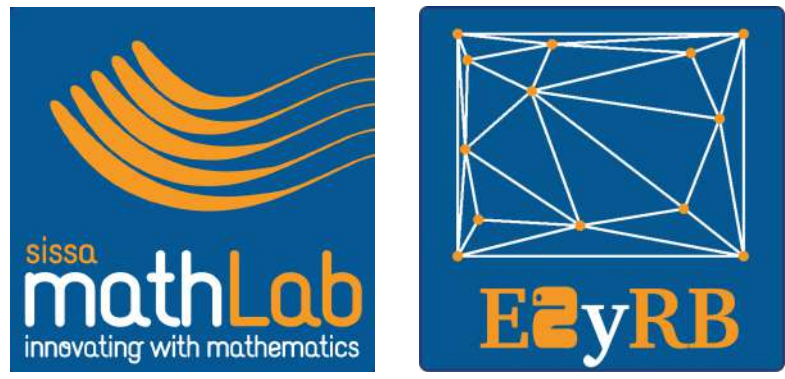


A machine learning-based reduced order model for the investigation of the haemodynamics in coronary artery bypass grafts

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Introduction

A machine learning **Reduced Order Model** (ROM) is developed in order to ensure rapid computations in a patient-specific **Coronary Artery Bypass Graft** (CABG). Both physical and geometrical parameters of clinical interest are introduced. An expensive offline phase performs a large number of high-fidelity solutions and generates the Reduced Basis (RB) with the **Proper Orthogonal Decomposition** (POD). Then, **feedforward Neural Networks** (NNs) are trained to interpolate the reduced coefficients. During the online stage, the behaviour of the system in the parameter space is available for real-time evaluation.

We consider two applications:

1. the ROM is implemented for the reconstruction of pressure, velocity and Wall Shear Stress (WSS) computed by the **Navier-Stokes** (N-S) equations. The inlet flow rate and the severity of the stenosis are considered as parameters in the reduced framework [2].
2. The ROM approach is used within an **Optimal Control Problem** (OCP) in order to match measured clinical data with numerical outcomes, varying the Reynolds (Re) number [4]. This approach is introduced to overcome the issues arising from unrealistic outlet boundary conditions, which can lead to doubtful predictions.

Full order model - 1

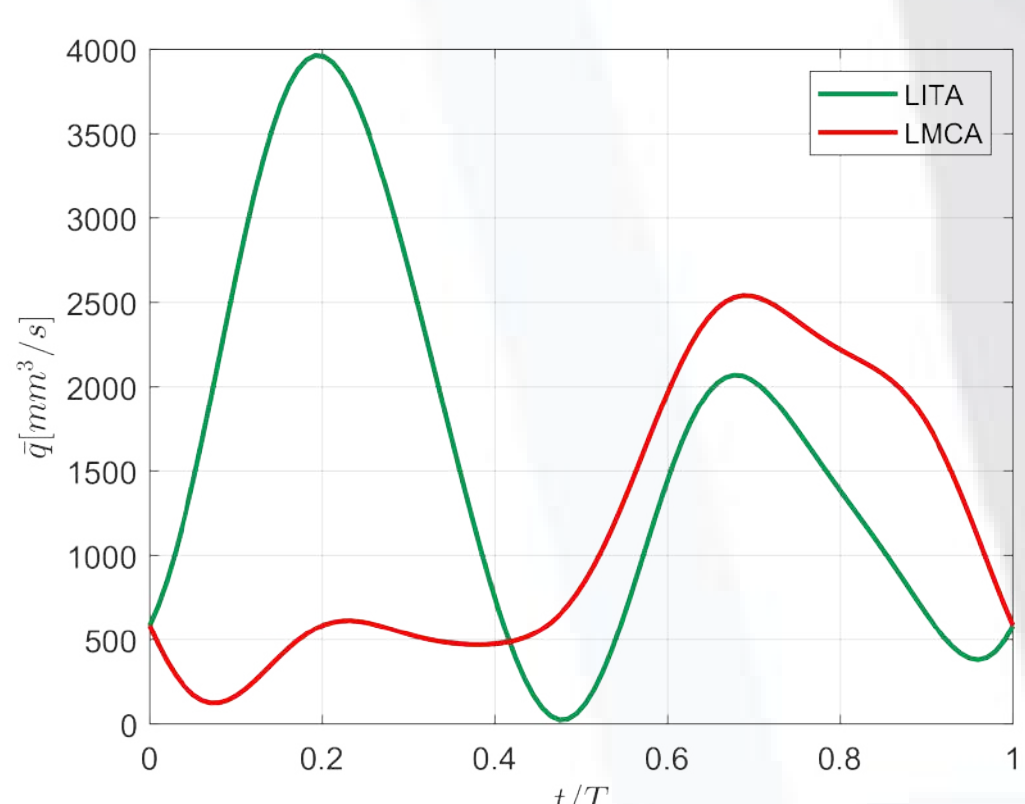
This work starts from [1], but it recasts the problem in a **Finite Volume** (FV) environment. Therefore, the geometrical parametrization of the domain changes accordingly.

The dynamics of the blood flow is described by parametrized incompressible N-S equations:

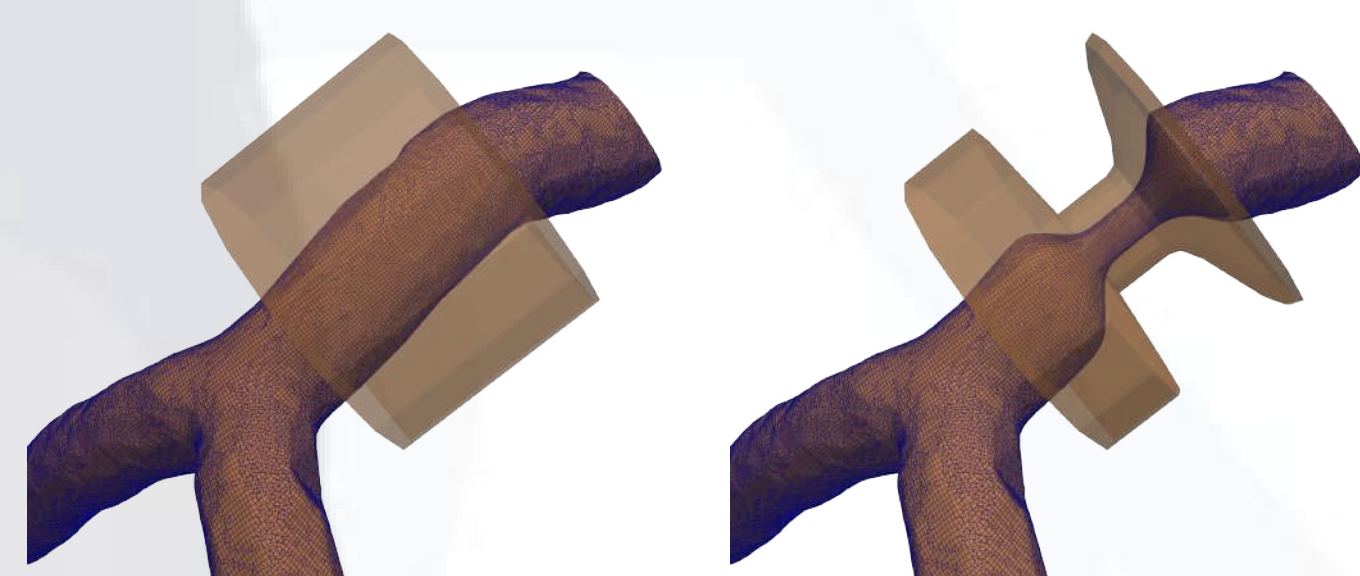
$$\begin{cases} \partial_t \mathbf{v}(\boldsymbol{\mu}) + \nabla \cdot (\mathbf{v}(\boldsymbol{\mu}) \otimes \mathbf{v}(\boldsymbol{\mu})) + \nabla p(\boldsymbol{\mu}) - \nu \Delta \mathbf{v}(\boldsymbol{\mu}) = 0, \\ \nabla \cdot \mathbf{v}(\boldsymbol{\mu}) = 0. \end{cases}$$

The parameters $\boldsymbol{\mu}$ are the **degree of the stenosis** in the Left Main Coronary Artery (LMCA) and the **inflow boundary conditions**.

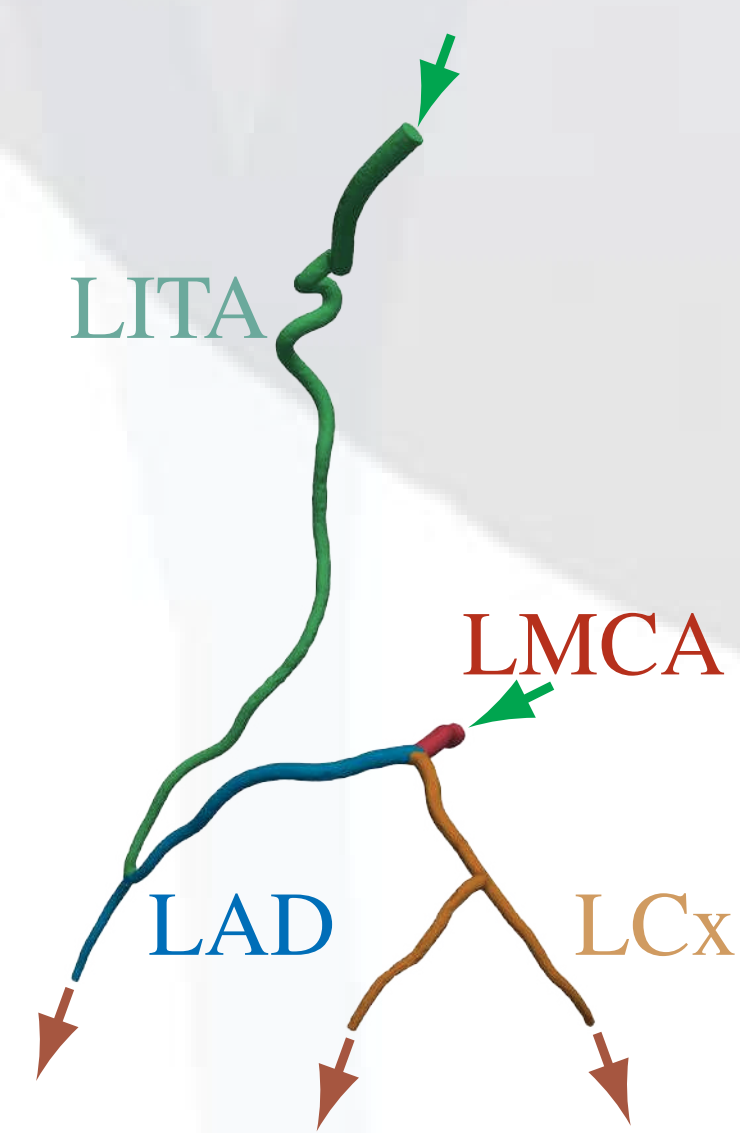
The boundary conditions are:



The **free form deformation** is used to introduce the stenosis in the LMCA:



OpenFOAM is used to find the FV high fidelity solutions, varying the parameters.



Optimal control approach - 2

Our OCP starts from [3] and finds the **Finite Element** (FE) solutions varying the inlet **Re** number.

The main ingredients are:

- (a) steady-state incompressible N-S equations

$$\begin{cases} -\nu \Delta \mathbf{v}(\boldsymbol{\mu}) + (\mathbf{v}(\boldsymbol{\mu}) \cdot \nabla) \mathbf{v}(\boldsymbol{\mu}) + \nabla p(\boldsymbol{\mu}) = 0, \\ \nabla \cdot \mathbf{v}(\boldsymbol{\mu}) = 0, \end{cases}$$

- (b) with boundary conditions

$$\begin{cases} \mathbf{v}(\boldsymbol{\mu}) = \mathbf{v}_{in}(\boldsymbol{\mu}), & \text{on } \Gamma_{inlet}, \\ -\nu (\nabla \mathbf{v}(\boldsymbol{\mu})) \mathbf{n} + p(\boldsymbol{\mu}) \mathbf{n} = \mathbf{u}(\boldsymbol{\mu}), & \text{on } \Gamma_{outlet}, \\ \mathbf{v}(\boldsymbol{\mu}) = 0, & \text{on } \Gamma_{wall}, \end{cases}$$

- (c) the **objective functional** to optimize is

$$\mathcal{J} = \frac{1}{2} \int_{\Omega} |\mathbf{v}(\boldsymbol{\mu}) - \mathbf{v}_m|^2 d\Omega + \frac{\alpha}{2} \int_{\Gamma_{outlet}} |\mathbf{u}(\boldsymbol{\mu})|^2 d\Gamma.$$

Given $\boldsymbol{\mu}$, find $(\mathbf{v}(\boldsymbol{\mu}), p(\boldsymbol{\mu}), \mathbf{u}(\boldsymbol{\mu}))$ such that the objective functional \mathcal{J} in (c) is minimized under the constrain (a)-(b).

In our work, the desired blood flow velocity and the boundary conditions are:

$$\mathbf{v}_{in} = \frac{\eta Re}{R_{in}} \left(1 - \frac{r^2}{R_{in}^2}\right) \mathbf{n}_{in}, \quad \mathbf{v}_m = v_{const} \left(1 - \frac{r^2}{R^2}\right) \mathbf{t}_c.$$

Python libraries **FEniCS** and **multiphenics** are used.



Reduced order model

The **POD-NN** is the **data-driven** method employed in these works to speed up high fidelity (FV and FE) simulations.

- Let $\bar{\Phi}$ be the variable of interest. The **POD** algorithm performs a SVD for the snapshots matrix:

$$S_{\Phi} = \begin{Bmatrix} \bar{\Phi}_1(\boldsymbol{\mu}_1) & \dots & \bar{\Phi}_1(\boldsymbol{\mu}_L) \\ \vdots & & \vdots \\ \bar{\Phi}_{N_{\delta}}(\boldsymbol{\mu}_1) & \dots & \bar{\Phi}_{N_{\delta}}(\boldsymbol{\mu}_L) \end{Bmatrix}.$$

The firsts $R \ll L$ left eigenvectors compose the RB:

$$V_{\delta} = [\mathbf{w}_1 | \dots | \mathbf{w}_R] \in \mathbb{R}^{N_{\delta} \times R}.$$

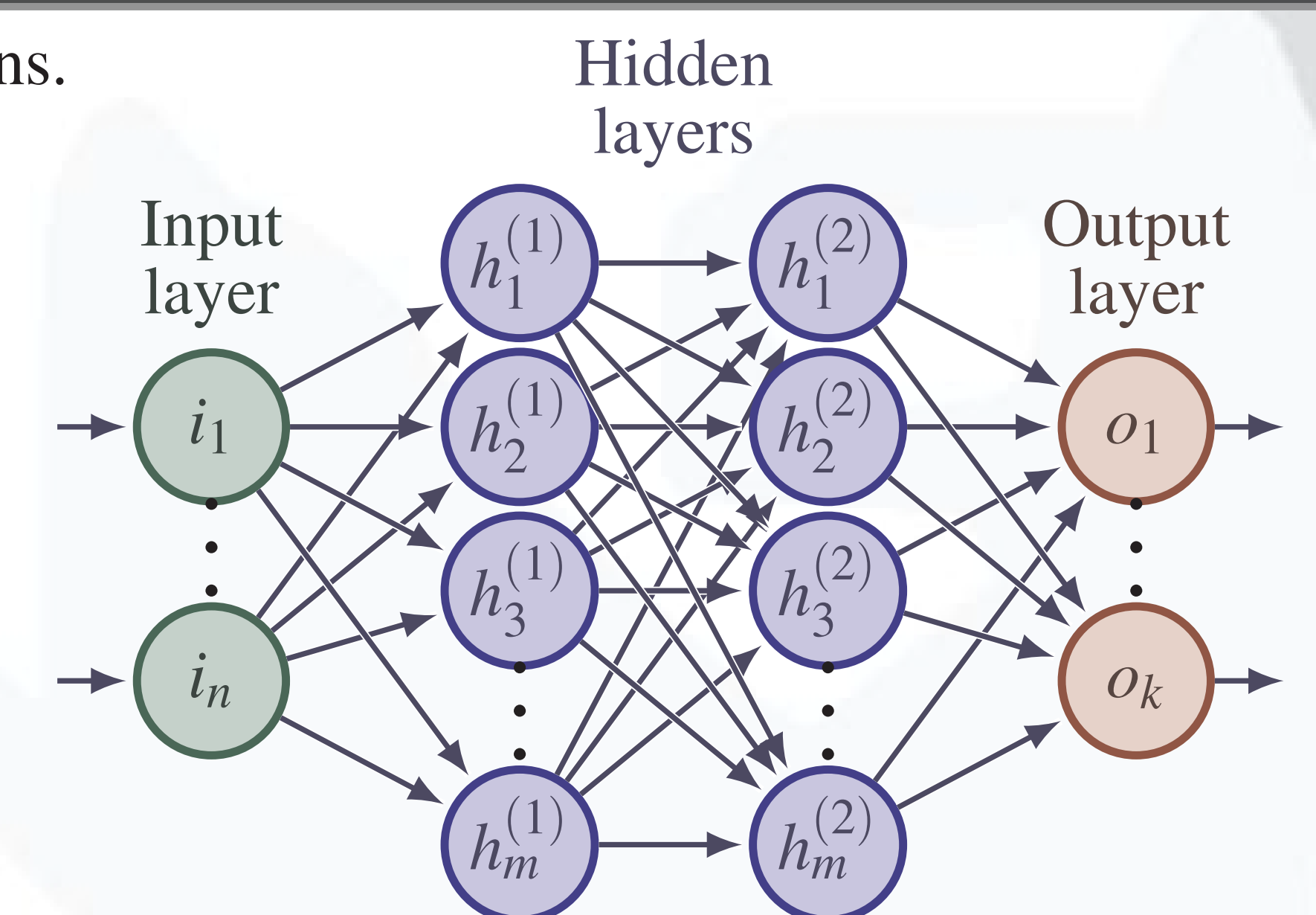
- Since the reduced solution is:

$$\Phi_r(\boldsymbol{\mu}_l) = \sum_{r=1}^R (V_{\delta}^T \bar{\Phi}(\boldsymbol{\mu}_l))_r \mathbf{w}_r, \quad l = 0, \dots, L,$$

an **interpolation** of the reduced coefficients

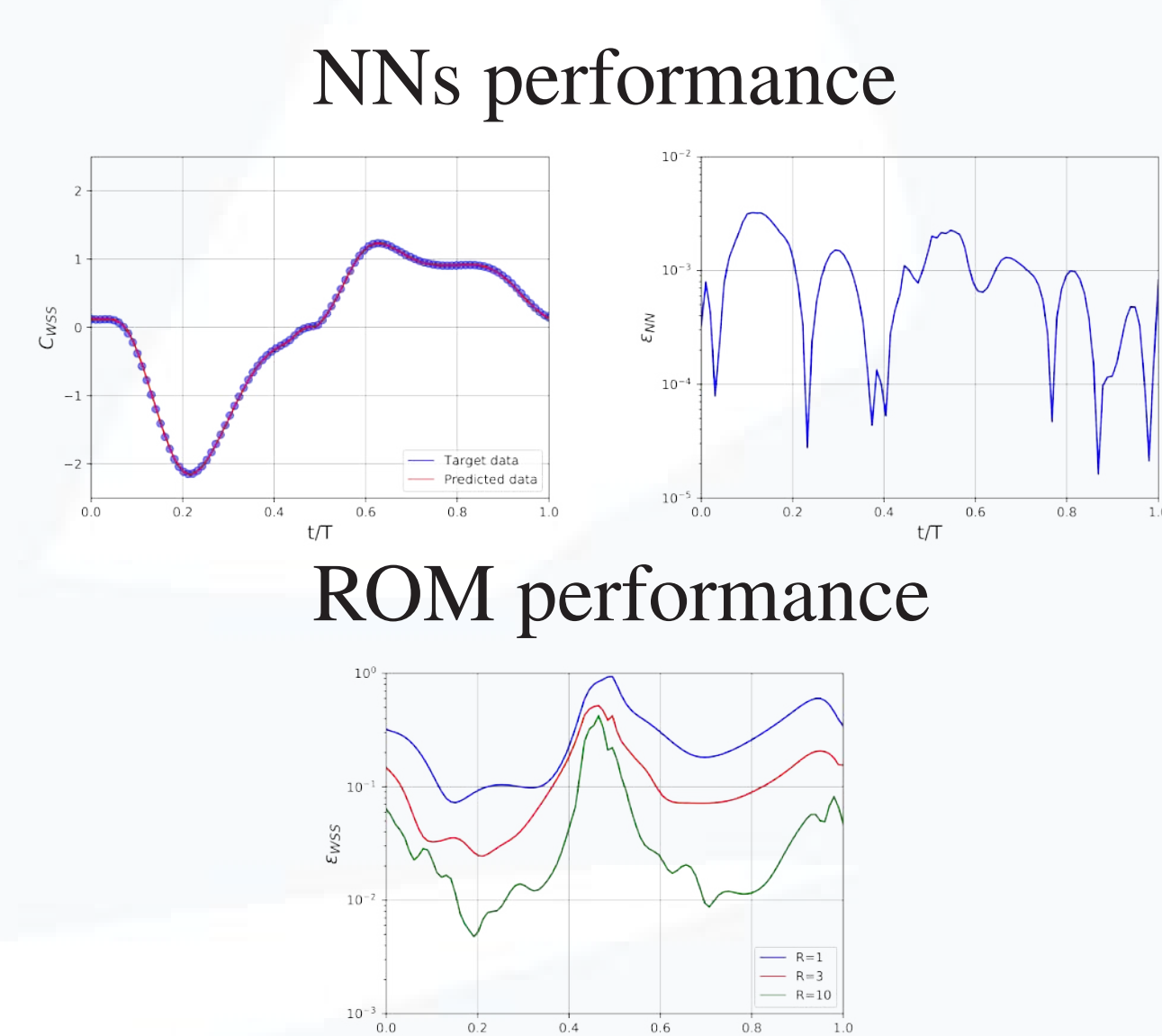
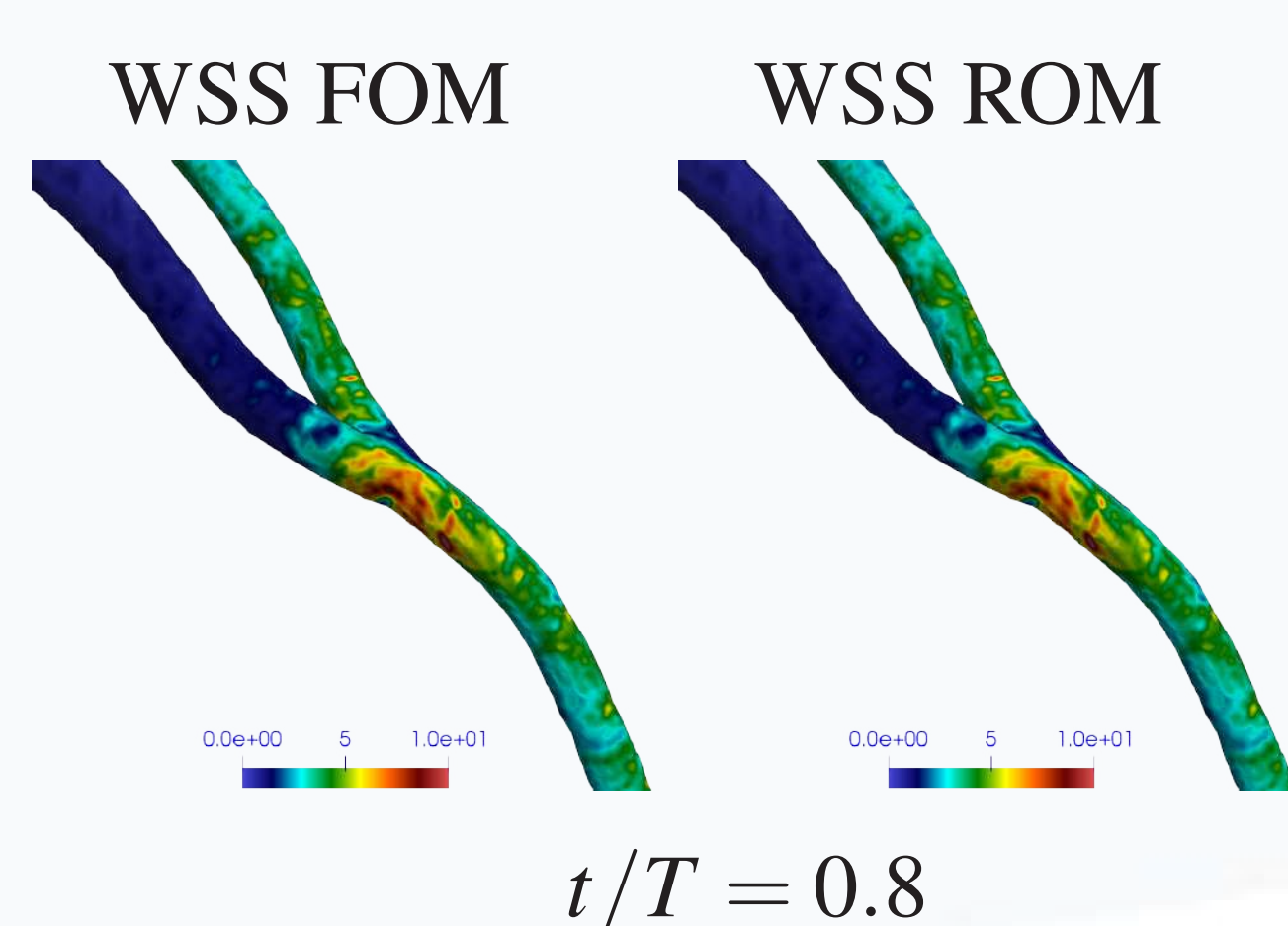
$$\boldsymbol{\pi} : \boldsymbol{\mu}_l \mapsto [(V_{\delta}^T \bar{\Phi}(\boldsymbol{\mu}_l))_r]_{r=1}^R, \quad l = 1, \dots, L,$$

is carried out through **feedforward NNs**.



Results - 1

The speed-up is about $\mathcal{O}(10^5)$.



Results - 2

The speed-up is $\mathcal{O}(10^6)$, 4 times larger than POD-Galerkin of [3].

